A Note on Quai - umbilical Hypersurface of a Sasakian Manifold with (ϕ, g, u, v, λ) – structure

Sachin Kumar Srivastava¹ and Alok Kumar Srivastava²

¹Department of Mathematics, Central University of Himachal Pradesh, Dharamshala-176215, India. E-mail: sachink.ddumath@gmail.com. ²Department of Mathematics, Govt. P.G. College, Chunar, Mirzapur-231304, India. E-mail: aalok_sri@yahoo.co.in)

Abstract

In this paper we have studied the properties of Quasi – umbilical hypersurface ^M of a Sasakian manifold \tilde{M} with (ϕ, g, u, v, λ) – structure and established the relation for ^M to be cylindrical.

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1. Introduction

Let \tilde{M} be a (2n + 1) - dimensional Sasakian manifold with a tensor field $\tilde{\phi}$ of type (1, 1), a fundamental vector field ξ and 1-form η such that

(**1.1**)
$$\eta(\xi) = 1$$

 $(1.2) \qquad \tilde{\phi}^2 = -\mathbf{I} + \eta \otimes \xi$

where I denote the Identity transformation.

(1.3) (a)
$$\eta \circ \tilde{\phi} = 0$$
 (b) $\tilde{\phi} \xi = 0$ (c) rank $(\tilde{\phi}) = 2n$

If \tilde{M} admits a Riemannian metric \tilde{g} , such that

- (1.4) $\tilde{g}(\tilde{\phi}X,\tilde{\phi}Y) = \tilde{g}(X,Y) \eta(X)\eta(Y)$
- (1.5) $\tilde{g}(X,\xi) = \eta(X)$

then \tilde{M} is said to admit a $(\tilde{\phi}, \xi, \eta, \tilde{g})$ - structure called Contact metric structure. If moreover,

(1.6) $(\tilde{\nabla}_{x}\tilde{\phi})Y = \tilde{g}(X,Y)\xi - \eta(Y)X$

(1.7)
$$\tilde{\nabla}_{x}\xi = -\tilde{\phi}X$$

where $\tilde{\nabla}$ denotes the Riemannian connection of the Riemannian metric \tilde{g} , then $(\tilde{M}, \tilde{\phi}, \xi, \eta, \tilde{g})$ is called a Sasakian manifold (see [9]). If we define 'F(X,Y) = $\tilde{g}(\tilde{\phi}X, Y)$, then in addition to above relation we find

- (1.8) F(X,Y) + F(Y,X) = 0
- (1.9) $F(X,\tilde{\phi}Y) = F(Y,\tilde{\phi}X)$
- (1.10) $F(\tilde{\phi}X,\tilde{\phi}Y) = F(X,Y)$

2. Hypersurface of a Sasakian manifold with (ϕ,g,u,v,λ) - structure

Let us consider a 2n-dimensional manifold M embedded in \tilde{M} with embedding $b: M \to \tilde{M}$. . The map b induces a linear map B (called Jacobian map), $b: T_{p} \to T_{b_{p}}$.

Let an affine normal N of M is in such a way that $\tilde{\phi}N$ is always tangent to the hypersurface and satisfying the linear transformations.

- (2.1) $\tilde{\phi}BX = B\phi X + u(X)N$
- (2.2) $\tilde{\phi}N = -BU$
- (2.3) $\xi = \mathsf{BV} + \lambda \mathsf{N}$

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(2.4) $\eta(BX) = v(X)$

Where ϕ is a (1, 1) - type tensor; U, V are vector fields; u, v are 1-form and λ is a C^{*} functions. If $u \neq 0$ then, M is called a non-invariant hypersurface of \tilde{M} (see [1] and [3]).

Operating (2.1), (2.2) and (2.3) and (2.4) by $\tilde{\phi}$ and using (1.1), (1.2) and (1.3) and taking tangent, normal parts separately, we get the following induced structure on M:

(2.5) (a)
$$\phi^2 X = -X + u(X)U + v(X)V$$

(b) $u(\phi X) = \lambda v(X), v(\phi X) = -\eta(N)u(X)$

- (c) $\phi U = -\eta(N)V$, $\phi V = \lambda U$
- (d) $u(U) = 1 \lambda \eta(N), u(V) = 0$

(e)
$$v(U) = 0, v(V) = 1 - \lambda \eta(N)$$

and from (1.4) and (1.5) we get the induced metric g on M, i.e.,

(2.6)
$$g(\phi X, \phi Y) = g(X, Y) - u(X)u(Y) - v(X)v(Y)$$

(2.7)
$$g(U,X) = u(X), g(V,X) = v(X)$$

If we consider $\eta(N) = \lambda$, we get the following structures on M:

(2.8) (a)
$$\phi^2 = -1 + u \otimes U + v \otimes V$$

(b) $u \circ \phi = \lambda v$, $v \circ \phi = -\lambda u$
(c) $\phi U = -\lambda V$, $\phi V = \lambda U$
(d) $u(U) = 1 - \lambda^2$, $u(V) = 0$
(e) $v(U) = 0$, $v(V) = 1 - \lambda^2$

A manifold M with a metric g satisfying (2.6), (2.7) and (2.8) is called manifold with (ϕ,g,u,v,λ) - structure (see [2] and [7]). Let ∇ be the induced connection on the hypersurface M of the affine connection $\tilde{\nabla}$ of \tilde{M} .

Now using Gauss and Weingarten's equations

- (2.9) $\tilde{\nabla}_{_{\mathrm{R}X}} \mathrm{BY} = \mathrm{B}\nabla_{_{\mathrm{X}}} \mathrm{Y} + \mathrm{h}(\mathrm{X},\mathrm{Y})\mathrm{N}$
- (2.10) $\tilde{\nabla}_{_{\text{RX}}} N = BHX + \omega(X)N$

Where g(HY,Z) = h(Y,Z), h and H are the second fundamental tensors of type (0, 2) and (1, 1), and ω is 1-form. Now differentiating (2.1), (2.2), (2.3) and (2.4) covariantly and using (2.9). (2.10), (1.6) and reusing (2.1), (2.2), (2.3) and (2.4), we get

- (2.11) $(\nabla_{y}\phi)(X) = v(X)Y g(X,Y)V h(X,Y)U u(X)HY$
- (2.12) $(\nabla_{Y} u)(X) = -h(\phi X, Y) u(X)\omega(Y) \lambda g(X, Y)$
- (2.13) $(\nabla_{Y} v)(X) = g(X, \phi Y) + \lambda h(X, Y)$
- (2.14) $\nabla_{\gamma} U = \omega(Y)U \phi HY \lambda Y$
- (2.15) $\nabla_{Y} V = \phi Y + \lambda H Y$
- (2.16) $h(Y,V) = u(Y) Y\lambda \lambda\omega(Y)$
- (2.17) h(Y,U) = -u(HY)

Since h(X,Y) = g(HX,Y), then from (1.5) and (2.17), we get

 $(2.18) \qquad h(Y,U) = 0 \Longrightarrow HU = 0.$

3. Quasi – umbilical hypersurface: If

(3.1) $h(X,Y) = \alpha g(X,Y) + \beta q(X)q(Y)$

where α,β are scalar functions and q is 1-form such that g(Q,X) = q(X), then M is called *Quasi* – *umbilical* hypersurface (see [9]). If $\alpha = 0$ and $\beta \neq 0$ then Quasi – umbilical hypersurface M is called *cylindrical* (see [9]). If $\alpha \neq 0$ and $\beta = 0$ then Quasi – umbilical hypersurface is called *totally umbilical*. If $\alpha = 0$ and $\beta = 0$ then Quasi – umbilical hypersurface is called *totally geodesic*.

Using (3.1) in (2.11), (2.12), (2.13), (2.14), (2.15), (2.16) and (2.17) we get

(3.2)
$$(\nabla_{Y}\phi)(X) = v(X)Y - g(X,Y)V - \{\alpha g(X,Y) + \beta q(X)q(Y)\}U - u(X)\{\alpha Y + \beta q(Y)Q\}$$

- (3.3) $(\nabla_{\gamma} u)(X) = -\{\alpha g(\phi X, Y) + \beta q(\phi X)q(Y)\} u(X)\omega(Y) \lambda g(X, Y)$
- (3.4) $(\nabla_{Y} v)(X) = g(X, \phi Y) + \lambda \{ \alpha g(X, Y) + \beta q(X)q(Y) \}$
- (3.5) $\nabla_{Y} U = \omega(Y)U \{\alpha \phi Y + \beta q(Y)Q\} \lambda Y$
- (3.6) $\nabla_{v} V = \phi Y + \lambda \{ \alpha Y + \beta q(Y) Q \}$
- (3.7) $h(Y,V) = \alpha g(V,Y) + \beta q(Y)q(V)$
- (3.8) $|u(Q)|^2 = -\frac{\alpha}{\beta}(1-\lambda^2)$

Also on a cylindrical hypersurface M with (ϕ,g,u,v,λ) - structure of a Sasakian manifold \tilde{M} , we have

(3.9)
$$v(\phi Q) = 0$$

(3.10) $u(Q) = 0 \Leftrightarrow q(U) = 0$

Main Result

Now we prove the following:

3.1 Theorem

On the Quasi – umbilical hypersurface M with (ϕ,g,u,v,λ) - structure of a Sasakian manifold \tilde{M} , we have

(3.11)
$$q(V) = v(Q) = 0$$

(3.12)
$$\omega(U) = \frac{1-\lambda^2}{\lambda} - \frac{U\lambda}{\lambda}$$

(3.13)
$$\omega(U) = -\alpha \frac{(1-\lambda^2)}{\lambda} - \frac{V\lambda}{\lambda}$$

Proof

Put X = U, Y = U in (3.1) and using (2.18), we have

$$\alpha(1-\lambda^2)+\beta |q(U)|^2=0 \Leftrightarrow |q(U)|^2=-\frac{\alpha}{\beta}(1-\lambda^2)$$

If we take X = V, Y = U in (3.1) then we get $\beta q(V)q(U) = 0$. Since $\beta \neq 0$ and $q(U) \neq 0$, therefore q(V) = v(Q) = 0 which proves (3.11).

Also from (3.1) and (2.16), we get

(3.14) $\alpha g(Y,V) + \beta q(Y)q(V) = u(Y) - Y\lambda - \lambda \omega(Y) \cdot$

Let Y = U and using g(U,V) = u(V) = 0, we get (3.12). Further putting Y = V in (3.14) we have (3.13).

If Quasi – umbilical hypersurface is cylindrical then from (3.13), we have $\omega = -d(\ell og \lambda)$. Therefore we can state the following theorem as a corollary of Theorem 3.1.:

3.1 Theorem

If Quasi – umbilical hypersurface M with (ϕ,g,u,v,λ) - structure of a Sasakian manifold \tilde{M} is cylindrical, then 1-form ω satisfies the following relation

 $\omega = -d(\ell og\lambda)$

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