Numerical Simulation of Flow Around An Elliptical Cylinder at High Reynolds Numbers

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Abstract

High Reynolds number flows (Re= 0.5×10^6 , 1×10^6 , 2×10^6 and 3.6×10^6 , based on the free stream velocity and cylinder diameter) covering the supercritical to upper-transition flow regimes around a two dimensional (2D) elliptical cylinder, have been investigated numerically using 2D Unsteady Reynolds-Averaged Navier–Stokes(URANS) equations with a standard high Reynolds number k- ε turbulence model. The objective of the present study is to evaluate the coefficient of drag along the outer surface of elliptical cylinder with minor-to-major axis ratios of 0.4, 0.6, and 0.8 for different types of velocity input e.g. uniform, parabolic, triangular and plain shear velocity profiles.

The results are compared with published data for circular cylinder in cross flow having uniform velocity. Drag of the elliptical cylinders is lower than a circular cylinder. Reductions in drag may be increased by making the streamlined cylinders more slender. Over the range of Reynolds number considered, an elliptical cylinder with an axis ratio equal to 0.6 reduces drag coefficient by 40 to 45 percent compared to that of a circular cylinder. Although the k- ε model is known to yield less accurate predictions of flows with strong anisotropic turbulence, satisfactory results for engineering design purposes are obtained for high Reynolds number flows around an elliptical cylinder in the supercritical and upper-transition flow regimes.

Keywords: elliptical cylinder; circular cylinder; cross flow; Unsteady RANS; High Reynolds number flows; Navier–Stokes equations.

Introduction

The phenomenon of flow separation and bluff body wakes has long been intensely studied because of its fundamental significance in flow physics and its practical importance in aerodynamic and hydrodynamic applications. Flow behind a circular cylinder has become the canonical problem for studying such external separated flows. Engineering applications, on the other hand, often involve flows over complex bodies like wings, submarines, missiles, and rotor blades, which can hardly be modeled as a flow over a circular cylinder. In such flows, parameters such as axis ratio, Reynolds number and initial velocity profile can greatly influence the nature of separation and coefficient of drag. A fundamental study of flow over a complex non-canonical object would therefore significantly augment our current under-standing of such flows. Due to the complicated nature of the flow, theoretical and experimental analysis is typically limited to flow at very low Reynolds number. Numerical simulations provide a promising approach to analyzing this problem.

Elliptical cylinders ranging from a circular cylinder to a flat plate with changes in axis ratio and provide a richer flow behavior characteristic. There have been a few numerical simulations of flows over elliptic cylinders. Among the few numerical results reported in the open literature are those of yoshihiro mochimaru [4] and Zhihua Li et al. [5]. Yoshihiro mochimaru [4] investigates the effect of Reynolds number and axis ratio on the coefficient of drag and flow streamline prediction for the flow at higher Reynolds number up to 10^5 . Zhihua Li et al.[5] applied K ω -SST model to study the effect of axis ratio on drag coefficient at Re up to 10^4 . In the absence of comprehensive experimental data for elliptic cylinders for Re $\ge 5 \times 10^5$, the present results are in most cases compared against corresponding experimental and numerical data for circular cylinders. Catalano et al. [3] applied 3D Large Eddy Simulation (LES) with wall modeling as well as URANS using the standard k- ε model of Launder and Spalding [14] with wall functions, for 0.5×10^6 <Re< 4×10^6 . Singh and Mittal [7] performed their studies for $100 < \text{Re} < 1 \times 10^7$ using a 2D LES method. Most of the results appear to yield satisfactory agreements with experimental data.

The main objective of the present study is to evaluate the effect of axis ratio and different types of velocity profiles on coefficient of drag, over an elliptical cylinder, using standard k- ε turbulence model, in the supercritical and upper-transition flow regimes and these results are compared with available experimental data and the numerical results for circular cylinder reported by Catalano et al. [3].

Mathematical formulation

Flow model

The Reynolds-averaged equations for conservation of mass and momentum are given by

$$\frac{\partial u_i}{\partial x_i} = 0$$

$$\frac{\partial u_i}{\partial t} + u_j \frac{\partial u_i}{\partial x_j} = -\frac{1}{\rho} \left(\frac{\partial p}{\partial x_i}\right) + v \frac{\partial^2 u_i}{\partial x_i^2} - \frac{\partial \overline{u_i u_j}}{\partial x_j}$$

Where i, j = 1, 2. Here x_1 and x_2 denote the horizontal and vertical directions,

respectively; u_1 and u_2 are the corresponding mean velocity components; P is the dynamic pressure; and ρ is the density of the fluid.

The Reynolds stress component, $\overline{u_1 u_j}$, is expressed in terms of a turbulent viscosity v_T and the mean flow gradients using the Boussinesq approximation,

$$-\overline{\mathbf{U}_{1}\mathbf{U}_{j}} = v_{\mathrm{T}}\left(\frac{\partial \mathbf{u}_{i}}{\partial \mathbf{x}_{j}} + \frac{\partial \mathbf{u}_{j}}{\partial \mathbf{x}_{i}}\right) - \frac{2}{3}k\delta_{ij}$$

Where k is the turbulent kinetic energy and δ_{ij} is the Kronecker delta function.

A standard high Reynolds number $k-\varepsilon$ turbulence model (see e.g. Launder and Spalding, 1972; Rodi, 1993) is used in the present study; the model has been applied previously on vortex shedding flow by Majumdar and Rodi (1985). The k and ε equations are given by:

$$\frac{\partial k}{\partial t} + u_{j}\frac{\partial k}{\partial x_{j}} = \frac{\partial}{\partial x_{j}}\left(\frac{v_{T}}{\sigma_{k}}\frac{\partial k}{\partial x_{j}}\right) + v_{T}\left(\frac{\partial u_{i}}{\partial x_{j}} + \frac{\partial u_{j}}{\partial x_{i}}\right)\frac{\partial u_{i}}{\partial x_{j}} - \varepsilon$$
$$\frac{\partial \varepsilon}{\partial t} + u_{j}\frac{\partial \varepsilon}{\partial x_{j}} = \frac{\partial}{\partial x_{j}}\left(\frac{v_{T}}{\sigma_{\varepsilon}}\frac{\partial \varepsilon}{\partial x_{j}}\right) + C_{1}\frac{\varepsilon}{k}v_{T}\left(\frac{\partial u_{i}}{\partial x_{j}} + \frac{\partial u_{j}}{\partial x_{i}}\right)\frac{\partial u_{i}}{\partial x_{j}} - C_{2}\frac{\varepsilon^{2}}{k}$$

Where $v_T = C_{\mu}(k^2/\epsilon)$.

The following standard model coefficients have been adopted: (C₁ =1.44, C₂=1.92, C_µ= 0.09, σ_k = 1.0, σ_ϵ = 1.3).

Numerical solution procedure, computational domain and boundary conditions

The Reynolds-averaged equations for conservation of mass and momentum, in conjunction with a standard high Reynolds number $k - \varepsilon$ model. A pressures based solver with 1st order discretization in time and 2nd order in spatial is used in this numerical simulation.

The geometric size of the rectangular computational domain and the boundary conditions imposed for all simulations are shown in Fig. 1. The size of the whole computational domain is $27D \times 14D$, where D is the diameter of base circular cylinder. The upper and lower boundaries are located at a distance 7D from the centre of the cylinder; this ensures that these boundaries have no effect on the flow around the cylinder. The flow inlet is located 7D upstream from the centre of the cylinder. These distances are sufficient to eliminate the far field effects on the flow upstream and downstream of the cylinder.



Fig. 1. Computational domain and the imposed boundary conditions

The boundary conditions used for the numerical simulations are as follows:

- (i) Uniform flow is specified at the inlet with $u_1 = U_{\infty}$, $u_2 = 0$. The free stream inlet turbulence values for kinetic energy $(k = (3/2)(I_u U_{\infty})^2)$ and turbulent dissipation $(\epsilon = (C_{\mu}k^{3/2})/(0.1L))$, proposed by Tutar and Holdø [8], have been imposed.
- (ii) Along the outflow boundary, u_1 , u_2 , k and ε are specified as free boundary conditions in a finite element context. This means that a traction-free velocity–pressure boundary condition is applied for u_1 , u_2 and P, while the flux is set equal to zero for k and ε .
- (iii) Along the upper and lower boundaries, u_1 , k and ε are free, while u_2 is set equal to zero.
- (iv) No-slip condition is applied on the cylinder surface with $u_1 = u_2 = 0$ and standard near-wall conditions are applied for k and ε near the cylinder wall (see e.g. Rodi, 1993) as

$$k = \frac{u^2_*}{\sqrt{C_u}}$$
, $\epsilon = C_{\mu}^{\frac{3}{4}} \frac{k^{\frac{3}{2}}}{kh_p}$

where hp is the radial distance between the first node and the wall, k = 0.41 is the von Karman constant, and u^{*} is the wall friction velocity obtained from the logarithmic (log) law.

$$\frac{u_{tan}}{u_*} = \frac{1}{k} \ln\left(\frac{9h_pu_*}{v}\right)$$

is applicable for $\frac{h_p u_*}{v} \ge 30$

Where $u_{tan} =$ tangential velocity to the wall.

Results and Discussion

The computations have been performed at Re= 0.5×10^6 , 1×10^6 , 2×10^6 and 3.6×10^6 , covering the supercritical to upper-transition flow regimes. The objective is to evaluate the coefficient of drag variations with minor to major axis ratio for different type of velocity input by using a standard high Reynolds number k - ε model around an elliptical cylinder and compared with published experimental data and numerical results of circular cylinder (minor to major axis ratio equal to 1).

The presentation which follows is structured to first validate the numerical approach and then to highlight the effect of axis ratio, λ_o , and various velocity profiles on drag coefficient.

Validation of Numerical Approach

The numerical approach is validated by comparing average values of drag coefficient to prior data for a circular cylinder with $\lambda_o = 1$. The overall drag coefficient is plotted as a function of Re in Fig. 2.



Fig. 2. Drag coefficient as a function of the Reynolds number. (—) Achenbach (1968); (●) LES; (■) URANS (●) present simulation.

The measured data were obtained for a free stream turbulence intensity of 0.8% and turbulent length scale of 0.0045 per unit diameter. The predicted drag coefficient for $0.5 \times 10^6 \leq \text{Re} \leq 2 \times 10^6$ agrees with the experimental and other numerical result but small discrepancies between the present results and the results reported by Catalano et al.[3] are seen at 3.6×10^6 . The present computed C_D decreases slightly as the Reynolds number increases, whereas the URANS and LES results reported by Catalano et al. exhibit a slight increase of C_D. This might be caused by different implementations of the wall function. The comparisons are shown in Table 1 for Re = 1×10^6 .

$Re = 1 \times 10^6$ (supercritical regime)	CD
Present simulation	0.39
Muk Chen Ong et al. k-epsilon	0.5174
Catalano et al. [3] 3D LES	0.31 -0.35
Catalano et al. [3] URANS	0.41
Singh and Mittal [21] 2D LES	0.591
Published experimental data	0.21-0.63

Table 1 comparision of numerical and experimental results.

Parametric Study

Attention is first turned to the effect of streamlined cylinder shape (axis ratio, λ_o) and different types of velocity profiles on coefficient of drag. Numerical results for elliptical cylinders with $\lambda_o = 0.4$, 0.6 and 0.8 at $0.5 \times 10^6 \leq \text{Re} \leq 3.6 \times 10^6$ are compared with the circular cylinders ($\lambda_o = 1$).

The results are interpreted to determine the conditions under which the shaped cylinder is feasible from the perspective of reducing drag in turbulent cross flow. The impact of Re within the range considered is significant for elliptical cylinders. For streamlined shapes, C_D decreases as the cylinders are slenderized, i.e. λ_o is decreased. For example, for an elliptical cylinder, C_D at $\lambda_o = 0.4$ is 25% lower than that at $\lambda_o = 0.6$ and 60% lower than the circular cylinder. Significant reductions in drag compared to that of the circular cylinder are possible for $\lambda_o \leq 0.6$. To illustrate this point, consider elliptical cylinders with $\lambda_o = 0.6$ at Re = 1×10^6 as shown in fig. 3; drag is reduced by 45% compared to the circular cylinder for any type of input velocity profile.



Fig. 3. Coefficient of drag variation with axis ratio at $\text{Re} = 10^6$.

For any streamlined cylinder, coefficient of drag for triangular and parabolic velocity input is greater than the uniform and shear velocity input as shown in fig. 3. C_D curve

for uniform and shear velocity overlaps each other. Coefficient of drag for shear velocity has slightly smaller value than uniform velocity. C_D for triangular velocity profile is 3 times and for parabolic profile is 1.75 times approximately as compared to uniform velocity.

The variations of coefficient of drag at various axis ratios with Reynolds number for different types of velocity profile are shown in fig. 4. This shows that C_D decreases as the Reynolds number increases at all axis ratio for any type of initial velocity profiles. These results show better agreement with experimental and numerical results.



Fig. 4. Coefficient of drag variation with Reynolds number.

Overall, the standard high Reynolds number k - ε model gives satisfactory predictions of the drag coefficient around a 2D circular and elliptical cylinder in the range Re = 0.5×10^6 to 3.6×10^6 . This is based on comparing the results with the published experimental data and numerical results. The results of the present study are encouraging for CFD-based engineering applications, e.g. submarine and wings because the URANS with the standard high Reynolds number k- ε model requires less computational effort compared with LES and DNS.

Conclusion

The numerical study of the drag around elliptical cylinders in cross flow with various input velocity profiles for $0.5 \times 10^6 \leq \text{Re} \leq 3.6 \times 10^6$ demonstrate the effects of using streamlined cylinders rather than circular cylinders in different engineering applications. Minor-to-major axis ratios (λ_0) equal to 0.4, 0.6 and 0.8, are considered for elliptical cylinder. Drag coefficient decreases, as the cylinders are made more slender, i.e. λ_0 is decreased. Compared with a circular tube, the drag coefficient is reduced by 40 to 45% by the use of an elliptical cylinder with $\lambda_0 = 0.6$ for any type of velocity profile.

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